

$$T = \frac{1}{2} m_1 (\dot{x}^2 + \dot{y}^2) + \frac{1}{2} m_2 \dot{z}^2$$

$$V = -m_2 g z$$

$$\text{constraint: } x^2 + y^2 = (l - z)^2 \text{ or } r + z = l$$

$$L = \frac{1}{2} m_1 (\dot{r}^2 + r^2 \dot{\theta}^2) + \frac{1}{2} m_2 \dot{z}^2 + m_2 g z = \frac{1}{2} m_1 (\dot{r}^2 + r^2 \dot{\theta}^2) + \frac{1}{2} m_2 \dot{r}^2 - m_2 g r$$

(ignore const)

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} = \frac{d}{dt} m_1 r^2 \dot{\theta} = 0 \Rightarrow l = m_1 r^2 \dot{\theta} \text{ const.}$$

$$L = \frac{1}{2} (m_1 + m_2) \dot{r}^2 + \frac{1}{2} m_1 r^2 \dot{\theta}^2 - m_2 g r$$

$$(m_1 + m_2) \ddot{r} - m_1 r \dot{\theta}^2 + m_2 g = 0, \quad \dot{\theta} = \frac{l}{m_1 r^2}$$

$$\Rightarrow (m_1 + m_2) \ddot{r} - \frac{l^2}{m_1 r^3} + m_2 g = 0$$

$$l = m_1 r^2 \dot{\theta} \text{ angular momentum conserved } (\theta \text{ symmetry})$$

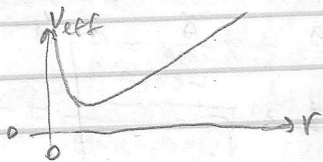
$$H = (m_1 + m_2) \dot{r}^2 + m_1 r^2 \dot{\theta}^2 - L = \frac{1}{2} (m_1 + m_2) \dot{r}^2 + \frac{1}{2} m_1 r^2 \dot{\theta}^2 + m_2 g r$$

energy conserved (time symmetry)

stationary circular orbit: $\dot{r} = 0, r = a$

$$m \frac{l^2}{m_1 a^3} = m_2 g \quad \text{i.e. } \sqrt{m_1 m_2 g a^3} = l (= m_1 a^2 \dot{\theta})$$

$$E = \frac{1}{2} (m_1 + m_2) \dot{r}^2 + \frac{l^2}{2 m_1 r} + m_2 g r \Rightarrow V_{\text{eff}} = \frac{l^2}{2 m_1 r} + m_2 g r$$



hanging mass pulled: l conserved (l still indep of θ)

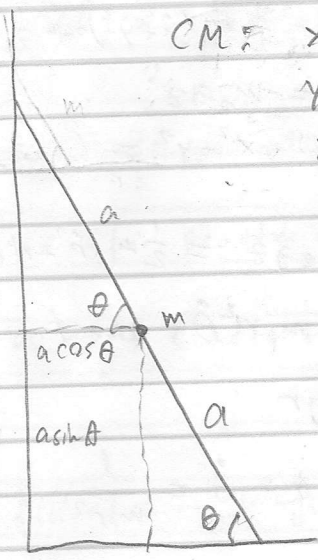
$$l = \sqrt{m_1 m_2 g a^3}, \quad r = a + q \rightarrow (m_1 + m_2) \ddot{q} - \frac{m_2 g a^3}{(a+q)^3} + m_2 g = 0$$

$$(m_1 + m_2) \ddot{q} + m_2 g \left(1 - \left(1 - \frac{3q}{a}\right)\right) = 0$$

$$\ddot{q} + \frac{3 m_2 g}{(m_1 + m_2) a} q = 0 \Rightarrow \omega = \sqrt{\frac{3 m_2 g}{(m_1 + m_2) a}}$$

$$\text{circular: } \omega_c = \dot{\theta} = \frac{l}{m_1 a^2} = \sqrt{\frac{m_2 g}{m_1 a}}, \quad \frac{\omega}{\omega_c} = \sqrt{\frac{3 m_1}{m_1 + m_2}}$$

2013 CM 2



CM: $x = a \cos \theta$ $T = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2) + \frac{1}{2} I \dot{\theta}^2$
 $y = a \sin \theta$ $I = \frac{1}{3} m a^3$
 $\dot{x}^2 + \dot{y}^2 = a^2 (\sin^2 \theta \dot{\theta}^2 + \cos^2 \theta \dot{\theta}^2) = a^2 \dot{\theta}^2$
 $\Rightarrow T = \frac{1}{2} m a^2 \dot{\theta}^2 + \frac{1}{6} m a^2 \dot{\theta}^2 = \frac{2}{3} m a^2 \dot{\theta}^2$

$V = m g a \sin \theta$

$E = \frac{2}{3} m a^2 \dot{\theta}^2 + m g a \sin \theta = E_0 = m g a \sin \theta_0$

$\Rightarrow \dot{\theta}^2 = \frac{3}{2} \frac{g}{a} (\sin \theta_0 - \sin \theta)$

$\frac{d\theta}{dt} = \sqrt{\frac{3g}{2a} (\sin \theta_0 - \sin \theta)}$

$t = \sqrt{\frac{2a^2}{3g}} \int_{\theta_0}^{\theta} \frac{d\theta'}{\sqrt{\sin \theta_0 - \sin \theta'}}$

vertical wall constraint is $x = a \cos \theta \Rightarrow dx + a \sin \theta d\theta = 0$

$L = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} m a^2 \cos^2 \theta \dot{\theta}^2 + \frac{1}{6} m a^2 \dot{\theta}^2 - m g a \sin \theta$

$m \ddot{x} = \lambda, \quad \frac{d}{dt} (m a^2 \cos^2 \theta \dot{\theta} + \frac{1}{3} m a^2 \dot{\theta}) - m g a \cos \theta = \lambda$
 $+ m a^2 \cos \theta \sin \theta \dot{\theta}^2 + m g a \cos \theta = a \sin \theta \lambda$

θ_1 at $\lambda = 0, \quad + \frac{1}{3} m a^2 \ddot{\theta}$

$m a^2 (-2 \cos \theta \sin \theta \dot{\theta}^2 + \cos^2 \theta \ddot{\theta}) + m a^2 \cos \theta \sin \theta \dot{\theta}^2 + m g a \cos \theta = 0$
 $-2 \sin \theta \dot{\theta}^2 + \cos \theta \ddot{\theta} + \sin \theta \dot{\theta}^2 + \frac{g}{a} + \frac{1}{3} \frac{\ddot{\theta}}{\cos \theta} = 0$

but $\dot{\theta} = \sqrt{\frac{3g}{2a} (\sin \theta_0 - \sin \theta)}$, $\ddot{\theta} = \sqrt{\frac{3g}{2a}} \frac{1}{2} \frac{-\cos \theta \dot{\theta}}{\sqrt{\sin \theta_0 - \sin \theta}} = -\frac{3g}{4a} \cos \theta$

$-\frac{3g}{4a} \cos^2 \theta - \frac{3g}{2a} \sin \theta (\sin \theta_0 - \sin \theta) + \frac{g}{a} - \frac{g}{4a}$

$(\frac{3}{4} + \frac{3}{2}) \sin^2 \theta + (-\frac{3}{2} \sin \theta_0) \sin \theta + (1 - \frac{3}{4} - \frac{1}{4}) = 0$

$\frac{9}{4} \sin^2 \theta - \frac{3}{2} \sin \theta_0 \sin \theta = 0$

$(3 \sin \theta - 2 \sin \theta_0) \sin \theta = 0 \Rightarrow \sin \theta = 0, \frac{2}{3} \sin \theta_0$

$\sin \theta_1 = \frac{2}{3} \sin \theta_0$

CM3 $I_i \dot{\omega}_i + \epsilon_{ijk} \omega_j \omega_k I_k = 0$ i.e.

$$I_1 \dot{\omega}_1 + (I_3 - I_2) \omega_2 \omega_3 = 0 \Rightarrow \dot{\omega}_1 = \frac{I_2 - I_3}{I_1} (\omega_2 \omega_3 + \omega_3 \dot{\omega}_2)$$

$$I_2 \dot{\omega}_2 + (I_1 - I_3) \omega_3 \omega_1 = 0 \quad \dot{\omega}_2 = \frac{I_3 - I_1}{I_2} (\omega_3 \omega_1 + \omega_1 \dot{\omega}_3)$$

$$I_3 \dot{\omega}_3 + (I_2 - I_1) \omega_1 \omega_2 = 0$$

$$\ddot{\omega}_1 = \frac{I_2 - I_3}{I_1} \left(\frac{I_3 - I_1}{I_2} \omega_3^2 \omega_1 + \frac{I_1 - I_2}{I_3} \omega_2^2 \omega_1 \right)$$

$$= \frac{I_2 - I_3}{I_1} \left(\frac{I_3 - I_1}{I_2} \omega_3^2 + \frac{I_1 - I_2}{I_3} \omega_2^2 \right) \omega_1$$

$$\ddot{\omega}_2 = \frac{I_3 - I_1}{I_2} \left(\frac{I_1 - I_2}{I_3} \omega_1^2 + \frac{I_2 - I_3}{I_1} \omega_3^2 \right) \omega_2$$

take $\omega_3 \Rightarrow \omega_2, \omega_1$

$$\ddot{\omega}_1 \approx \frac{I_2 - I_3}{I_1} \frac{I_3 - I_1}{I_2} \omega_3^2 \omega_1, \quad \ddot{\omega}_2 \approx \frac{I_3 - I_1}{I_2} \frac{I_2 - I_3}{I_1} \omega_3^2 \omega_2$$

$$\Rightarrow \ddot{\omega}_1 - a^2 \omega_1 \approx 0, \quad \ddot{\omega}_2 - a^2 \omega_2 \approx 0, \quad a^2 = \frac{I_2 - I_3}{I_1} \frac{I_3 - I_1}{I_2}$$

I_3 largest $\Rightarrow a^2 < 0 \Rightarrow \omega_{1,2} \sim e^{i|a|t}$, stable

I_3 smallest \Rightarrow same

I_3 middle $\Rightarrow a^2 > 0 \Rightarrow \omega_{1,2} \sim e^{\pm a t}$, unstable

CM4 $\frac{\partial Q}{\partial q} = \cos \phi, \quad \frac{\partial Q}{\partial p} = -\sin \phi, \quad \frac{\partial P}{\partial q} = \sin \phi, \quad \frac{\partial P}{\partial p} = \cos \phi$

$$M = \begin{pmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{pmatrix}, \quad J = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

$$M J M^T = \begin{pmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} \cos \phi & \sin \phi \\ -\sin \phi & \cos \phi \end{pmatrix} = \begin{pmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{pmatrix} \begin{pmatrix} -\sin \phi & \cos \phi \\ -\cos \phi & -\sin \phi \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \quad \text{is canonical for all } \phi.$$

note $p = \frac{\partial L}{\partial \dot{q}} = \frac{\partial}{\partial \dot{q}} \left(\frac{1}{2} m \dot{q}^2 + \frac{1}{2} I \dot{\phi}^2 + m g l \cos \phi \right) = m \dot{q} + I \dot{\phi}$

$$\frac{\partial F}{\partial q} = \frac{1}{2} \frac{m \cos^2 \phi}{\sin^4 \phi} + \frac{1}{2} \frac{m g \cos \phi}{\sin^4 \phi} = \frac{\partial F}{\partial q}$$

$$\Rightarrow \dot{q} = \frac{1}{m} p - \frac{I}{m} \dot{\phi} + f(q)$$

$$\Rightarrow \frac{\partial F}{\partial x} = -\frac{p}{m} + \frac{\partial f(q)}{\partial x} = \frac{\partial F}{\partial x} + \frac{\partial f(q)}{\partial x}$$

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$$p = \frac{\partial F_1(q, Q)}{\partial q} = q \frac{\cos \phi}{\sin \phi} - Q \frac{1}{\sin \phi} \Rightarrow F_1 = \frac{q^2}{2} \frac{\cos \phi}{\sin \phi} - \frac{qQ}{\sin \phi} + f(Q)$$

$$-P = \frac{\partial F_1}{\partial Q} = -q \sin \phi - q \frac{\cos^2 \phi}{\sin \phi} + Q \frac{\cos \phi}{\sin \phi} = -\frac{q}{\sin \phi} + Q \frac{\cos \phi}{\sin \phi}$$

$$= -\frac{q}{\sin \phi} + \frac{\partial f}{\partial Q} \Rightarrow f(Q) = \frac{Q^2}{2} \frac{\cos \phi}{\sin \phi} + \text{ignore}$$

$$F_1(q, Q) = \frac{q^2}{2} \frac{\cos \phi}{\sin \phi} - \frac{qQ}{\sin \phi} + \frac{Q^2}{2} \frac{\cos \phi}{\sin \phi}$$

$$= \frac{(q^2 + Q^2)}{2} \cot \phi - qQ \csc \phi$$

$$H = p^2 + Q^2 = q^2 + p^2 + 2pq \sin \phi \cos \phi - 2pq \cos \phi \sin \phi$$

$$= p^2 + q^2$$

H is cyclic in ϕ . Period of ϕ is 2π so

take $\frac{\phi}{2\pi} = w$, angle variable.

$$J = \oint p dq = \oint \sqrt{H - q^2} dq = \sqrt{H} \oint \sqrt{1 - \left(\frac{q}{\sqrt{H}}\right)^2} \sqrt{H} d\left(\frac{q}{\sqrt{H}}\right)$$

$$= H \oint dx \sqrt{1 - x^2}, \quad x = \sin \theta, \quad dx = \cos \theta d\theta$$

$$= H \int \cos^2 \theta d\theta = \pi H$$

CM5 $\dot{x}^2 = l^2(2\dot{\phi} + 2\cos(2\phi)\dot{\phi})^2$ $\dot{z}^2 = l^2(2\sin(2\phi)\dot{\phi})^2$
 $\dot{x}^2 + \dot{z}^2 = 4l^2(\dot{\phi}^2 + 2\dot{\phi}^2\cos(2\phi) + \dot{\phi}^2) = 8l^2\dot{\phi}^2(1 + \cos(2\phi))$
 $\underbrace{2\cos^2\phi}$

$T = 4ml^2\dot{\phi}^2(1 + \cos(2\phi))$, $V = mglz = mgl(1 - \cos(2\phi))$
 $L = 4ml^2\dot{\phi}^2(1 + \cos(2\phi)) - mgl(1 - \cos(2\phi))$ $\underbrace{2\sin^2\phi}$

$p_\phi = \frac{\partial L}{\partial \dot{\phi}} = 8ml^2\dot{\phi}(1 + \cos(2\phi)) \Rightarrow H = 4ml^2\dot{\phi}^2(1 + \cos(2\phi)) + mgl(1 - \cos(2\phi))$

$H = \frac{p_\phi^2}{16ml^2(1 + \cos(2\phi))} + mgl(1 - \cos(2\phi))$

$p_\phi = \frac{\partial S}{\partial \phi} \rightarrow \frac{1}{16ml^2(1 + \cos(2\phi))} \left(\frac{\partial S}{\partial \phi} \right)^2 + mgl(1 - \cos(2\phi)) + \frac{\partial S}{\partial t} \stackrel{-E}{=} 0$

$\left(\frac{\partial S}{\partial \phi} \right)^2 = 16ml^2(1 + \cos(2\phi)) [-mgl(1 - \cos(2\phi)) + E] = 0$

$S = 4l\sqrt{m} \int d\phi \sqrt{(1 + \cos(2\phi))(E - mgl(1 - \cos(2\phi)))} - Et \quad \left(\frac{\partial S}{\partial E} = \beta \right)$

$4l\sqrt{m} \int d\phi \sqrt{(1 + \cos(2\phi))} \frac{1}{\sqrt{E - mgl(1 - \cos(2\phi))}} = \beta + t$

$\Rightarrow \int d\phi \sqrt{\frac{1 + \cos(2\phi)}{E - mgl(1 - \cos(2\phi))}} = \frac{t + \beta}{2l\sqrt{m}} = \sqrt{2} \int \frac{\cos\phi d\phi}{\sqrt{E - 2mgl\sin^2\phi}}$

$= \sqrt{\frac{2}{E}} \int \frac{du}{\sqrt{1 - au^2}} = \sqrt{\frac{2}{Ea}} \int \frac{dv}{\sqrt{1 - v^2}} = \sqrt{\frac{1}{mgl}} \sin^{-1} \left(\sqrt{\frac{2mgl}{E}} \sin\phi \right)$

$u = \sin\phi, a = \frac{2mgl}{E}, v = \sqrt{a}u \Rightarrow \sqrt{\frac{2mgl}{E}} \sin\phi = \sin\left(\frac{1}{\sqrt{2}}\sqrt{\frac{g}{l}}(t + \beta)\right)$

\rightarrow oscillates for $E < 2mgl$, bifurcates for $E = 2mgl$, inverted $E > 2mgl$

$J = \oint \sqrt{16ml^2(1 + \cos(2\phi))} \sqrt{E - mgl(1 - \cos(2\phi))} d\phi$ $\sin\theta = \sqrt{\frac{2mgl}{E}} \sin\phi$
 $= 4l\sqrt{2mE} \oint \cos\phi d\phi \sqrt{1 - \frac{2mgl}{E}\sin^2\phi} = \frac{4lE}{gl} \oint \cos^2\theta d\theta = 4\pi E \sqrt{\frac{l}{g}}$ $\cos\theta d\theta = \sqrt{\frac{2mgl}{E}} \cos\phi d\phi$

adiabatic: $J = 4\pi E \sqrt{\frac{l}{g}}$ constant $\Rightarrow E l^{1/2} = \text{const} \Rightarrow E \propto l^{-1/2}$

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SM 1

$\Omega(N,T) = \sum_{\text{states}} e^{-\beta E_s}$
 $Q(N,T) = \sum_{\text{config}} e^{-\beta E} \sim \Omega(N,T)^{N_{ad}}$ (non-interacting)

$A = -kT \ln Q(N,T) = -kT \ln \Omega(N,T)^{N_{ad}}$

$\Omega(N,T) = \frac{N_0!}{N_{ad}!(N_0 - N_{ad})!}$ (all single particle states)

N_{ad} particles
 N_0 sites
 ways to fill sites so weight config with N_{ad} particles by this.

$$Q(N,T) = \frac{N_0!}{N_{ad}!(N_0 - N_{ad})!} \Omega(N,T)^{N_{ad}}$$

$$A = -kT \ln Q = -kT (N_0 \ln N_0 - N_0 - N_{ad} \ln N_{ad} + N_{ad} - (N_0 - N_{ad}) \ln (N_0 - N_{ad}) + (N_0 - N_{ad}) + N_{ad} \ln \Omega(N,T))$$

$$= kT [N_0 (\ln(N_0 - N_{ad}) - \ln N_0) + N_{ad} (\ln N_{ad} - \ln(N_0 - N_{ad}) - \ln \Omega(N,T))]$$

$$M_{ad} = \frac{\partial A}{\partial N_{ad}} = kT \left[\frac{-N_0}{N_0 - N_{ad}} + \ln N_{ad} - \ln(N_0 - N_{ad}) - \ln \Omega(N,T) + 1 + \frac{N_{ad}}{N_0 - N_{ad}} \right]$$

$$= kT \ln \left[\frac{N_{ad}}{(N_0 - N_{ad}) \Omega(N,T)} \right] = M_{gas} = kT \ln \left[\frac{N - N_{ad}}{V} \left(\frac{h^2}{2\pi m kT} \right)^{3/2} \right]$$

$$\Rightarrow \frac{N - N_{ad}}{V} \left(\frac{h^2}{2\pi m kT} \right)^{3/2} = \frac{N_{ad}}{(N_0 - N_{ad}) \Omega(N,T)}$$

SM 2 $\Phi = -PV = kT \sum_{\epsilon} \ln(1 - e^{-\epsilon/kT}) = kT \int d\epsilon a(\epsilon) \ln(1 - e^{-\epsilon/kT})$

$$a(\epsilon) = \frac{V}{h^3} \frac{8\pi}{3} \frac{1}{c^3} 3\epsilon^2 = 8\pi \frac{V}{c^3 h^3} \epsilon^2$$

$$\Phi = \frac{8\pi V}{h^3 c^3} kT \int d\epsilon \epsilon^2 \ln(1 - e^{-\epsilon/kT})$$

$$S = -\frac{\partial \Phi}{\partial T} = -\frac{8\pi V}{h^3 c^3} k \int \epsilon^2 d\epsilon \left[\ln(1 - e^{-\epsilon/kT}) - T \frac{\frac{\epsilon/kT e^{-\epsilon/kT}}{1 - e^{-\epsilon/kT}}}{1 - e^{-\epsilon/kT}} \right]$$

$$= \frac{-8\pi V}{(hc)^3} k \left[\underbrace{\int_0^{\infty} \epsilon^2 d\epsilon \ln(1 - e^{-\epsilon/kT})}_{I_1} - \frac{1}{kT} \underbrace{\int_0^{\infty} \frac{\epsilon^3 d\epsilon}{e^{\epsilon/kT} - 1}}_{I_2} \right]$$

$$I_1 = - \int_0^{\infty} \frac{1}{3} \epsilon^3 d\epsilon \frac{\frac{1}{kT} e^{-\epsilon/kT}}{1 - e^{-\epsilon/kT}} = \frac{-1}{3kT} \int_0^{\infty} \frac{\epsilon^3 d\epsilon}{e^{\epsilon/kT} - 1} = \frac{-I_2}{3kT}$$

$x = \epsilon/kT \Rightarrow \epsilon = kT x$

$$S = \frac{32 \pi V}{3(hc)^3} \frac{I_2}{T}, \quad I_2 = (kT)^4 \frac{\pi^4}{15}$$

$$S = \frac{32 \pi^5 k^4}{45(hc)^3} VT^3$$

SM3 $Q_1 = 1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon}$, noninteracting + distinguishable \Rightarrow

$$Q_N = (1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon})^N$$

$$A = -kT \log Q_N = -NkT \log (1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon}), \quad \beta = \frac{1}{kT}$$

$$U = - \frac{\partial}{\partial \beta} \log Q_N = -N \frac{\partial}{\partial \beta} \log (1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon}) = -N \frac{-\epsilon e^{-\beta\epsilon} - 2\epsilon e^{-2\beta\epsilon}}{1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon}}$$

$$= N\epsilon \frac{e^{-\beta\epsilon} + 2e^{-2\beta\epsilon}}{1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon}}, \quad \beta = \frac{1}{kT}$$

$$A = U - TS \Rightarrow S = \frac{1}{T}(U - A) = N \left[\frac{\epsilon}{T} \frac{e^{-\beta\epsilon} + 2e^{-2\beta\epsilon}}{1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon}} + k \log (1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon}) \right]$$

$$C_V = \frac{\partial U}{\partial T} = \frac{d\beta}{dT} \frac{\partial U}{\partial \beta} = -\frac{1}{kT^2} \frac{\partial U}{\partial \beta}$$

$$= -\frac{1}{kT^2} \frac{(-\epsilon e^{-\beta\epsilon} - 4\epsilon e^{-2\beta\epsilon})(1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon}) - (e^{-\beta\epsilon} + 2e^{-2\beta\epsilon})(-\epsilon e^{-\beta\epsilon} - 2\epsilon e^{-2\beta\epsilon})}{(1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon})^2}$$

$$= \frac{\epsilon}{kT^2} \frac{e^{-\beta\epsilon} + e^{-2\beta\epsilon} + 4e^{-3\beta\epsilon} + 4e^{-2\beta\epsilon} + 4e^{-3\beta\epsilon} + 4e^{-4\beta\epsilon} - e^{-\beta\epsilon} - 2e^{-2\beta\epsilon} - 2e^{-3\beta\epsilon} - 4e^{-4\beta\epsilon}}{(1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon})^2}$$

$$= \frac{\epsilon}{kT^2} \frac{e^{-\beta\epsilon} (1 + 4e^{-\beta\epsilon} + e^{-2\beta\epsilon})}{(1 + e^{-\beta\epsilon} + e^{-2\beta\epsilon})^2}, \quad \beta = \frac{1}{kT}$$

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SM 4

$$NL = \sum_{i,j=1}^N \sigma_i \sigma_j \quad \sum_{n,n'} \sigma_i \sigma_j = \frac{1}{2} \sum_{i=1}^N \sigma_i \sum_{j=1}^N \sigma_j = N_{++} + N_{--} - N_{+-}$$

note $N_{++} + N_{--} + N_{+-} = \frac{q}{2} N$ $\left. \begin{aligned} 2N_{--} + N_{+-} &= qN_- \\ 2N_{++} + N_{+-} &= qN_+ \end{aligned} \right\}$

$$\Rightarrow N_{+-} = qN_+ - 2N_{++}$$

$$N_{--} = \frac{1}{2}(qN_- - N_{+-}) = \frac{q}{2}N_- - \frac{q}{2}N_+ + N_{++}$$

$$\begin{aligned} \Rightarrow \sum_{n,n'} \sigma_i \sigma_j &= 4N_{++} + \frac{q}{2}(N_- - N_+) - qN_+ \\ &= 4N_{++} - \frac{q}{2}N + q(N_- - N_+) = 4N_{++} - qNL - \frac{1}{2}qN \end{aligned}$$

$$\Rightarrow H = -J(4N_{++} - qNL - \frac{1}{2}qN) - BMNL$$

takes ratio of ++ pairs to total pairs as the same as probability that any two selected sites are +, i.e. the + sites are randomly distributed.

$$U = \bar{H} = -J(2qN \left(\frac{N_+}{N}\right)^2 - qNL - \frac{1}{2}qN) - BMNL$$

$$NL = N_+^2 - N_-^2 = 2N_+^2 - N \Rightarrow (NL)^2 = 4N_+^4 - 4N_+^2N + N^2 = 4N_+^4 - N(2NL + N)$$

$$N_+^2 = \frac{1}{4}N^2L^2 + \frac{1}{2}N^2L + \frac{1}{4}N^2$$

$$U = -qJN \left(\frac{1}{2}L^2 + L + \frac{1}{2} - L - \frac{1}{2} \right) - BMNL$$

$$= -\frac{1}{2}qJNL^2 - MBNL$$

SMS $Q_N = \sum_r e^{-\beta E_r} = \sum_{\{n_\epsilon\}} e^{-\beta \sum_\epsilon n_\epsilon \epsilon}$

$$Q = \sum_{N=0}^{\infty} \sum_{\{n_\epsilon\}} z^N e^{-\beta \sum_\epsilon n_\epsilon \epsilon} = \sum_{\substack{\{n_\epsilon\} \\ 0 \text{ or } 1}} z^{\sum_\epsilon n_\epsilon} e^{-\beta \sum_\epsilon n_\epsilon \epsilon}$$

$$= \prod_{\epsilon} \sum_{n_\epsilon} (ze^{-\beta \epsilon})^{n_\epsilon} = \prod_{\epsilon} (1 + ze^{-\beta \epsilon}) \quad z = e^{\beta \mu}$$

$$Q = \prod_p (1 + e^{-\beta(\epsilon_p - \mu)})$$

$$Q = \sum_N \sum_{\text{config } r} e^{\beta \mu N - \beta E_r}, \quad N = \frac{1}{\beta} \frac{d \log Q}{d \mu} = \frac{1}{\beta} \frac{d}{d \mu} \log Q$$

$$N = \frac{1}{\beta} \sum_p \frac{\beta e^{-\beta(\epsilon_p - \mu)}}{1 + e^{-\beta(\epsilon_p - \mu)}} = \sum_p \frac{1}{e^{\beta(\epsilon_p - \mu)} + 1}$$

$$\langle n_p \rangle = \frac{1}{e^{\beta(\epsilon_p - \mu)} + 1} \rightarrow \frac{1}{2}, \quad T \rightarrow \infty$$

$$\rightarrow \begin{cases} 0, & \epsilon_p > \mu \\ 1, & \epsilon_p < \mu \end{cases} \quad \text{for } T \rightarrow 0$$

$$E - \mu N = -\frac{\partial}{\partial \beta} \log Q = -\sum_p \frac{(\epsilon_p - \mu) e^{-\beta(\epsilon_p - \mu)}}{1 + e^{-\beta(\epsilon_p - \mu)}} = \sum_p \frac{\epsilon_p}{e^{\beta(\epsilon_p - \mu)} + 1} - \mu N$$

$$PV = kT \sum_p \log(1 + e^{-\beta(\epsilon_p - \mu)}), \quad \sum_p \rightarrow \frac{V}{h^3} \int 4\pi p^2 dp$$

$$= kT \frac{V}{h^3} 4\pi \int_0^\infty p^2 dp \log(1 + e^{-\beta(\frac{p^2}{2m} - \mu)})$$

$$= -kT \frac{V}{h^3} 4\pi \int_0^\infty \frac{1}{3} p^3 dp \frac{-\beta/m p e^{-\beta(\frac{p^2}{2m} - \mu)}}{1 + e^{-\beta(\frac{p^2}{2m} - \mu)}}$$

$$= \frac{2}{3} \frac{V}{h^3} \int_0^\infty 4\pi p^2 dp \frac{\frac{p^2}{2m}}{e^{\beta(\frac{p^2}{2m} - \mu)} + 1} = \frac{2}{3} \sum_p \frac{\epsilon_p}{e^{\beta(\epsilon_p - \mu)} + 1} = \frac{2}{3} E$$

$$PV = kT \frac{V}{h^3} 4\pi \int_0^\infty p^2 dp \log(1 + z e^{-p^2/2m})$$

$$\underbrace{z e^{-p^2/2m} - \frac{1}{2} z^2 e^{-p^2/m}}_{z e^{-p^2/2m} - \frac{1}{2} z^2 e^{-p^2/m}} + \mathcal{O}(z^3)$$

$$\approx c_0 + c_1 z + c_2 z^2 + \mathcal{O}(z^3)$$

$$c_0 = 0, \quad c_1 = kT \frac{V}{h^3} 4\pi \int_0^\infty p^2 e^{-p^2/2m} dp = \frac{4\pi kTV}{h^3} (2m)^{3/2} \int_0^\infty x^2 e^{-x^2} dx$$

$$c_2 = -\frac{2\pi kTV}{h^3} \int_0^\infty p^2 e^{-p^2/m} dp = -\frac{2\pi kTV}{h^3} m^{3/2} \int_0^\infty x^2 e^{-x^2} dx$$

$$\text{where } \int_0^\infty x^2 e^{-x^2} dx = \frac{1}{2} \int_0^\infty x d(e^{-x^2}) = \frac{1}{2} \int_0^\infty e^{-x^2} dx = \frac{\sqrt{\pi}}{4}$$

2013 EMI-1 $\nabla^2 \Phi = -\frac{\rho}{\epsilon_0}$, $\nabla^2 G(\vec{x}, \vec{x}') = -4\pi \delta^3(\vec{x} - \vec{x}')$

$$\int_V \Phi \nabla^2 G dV' = -4\pi \Phi(\vec{x}) = \oint_{\partial V} \Phi \nabla G \cdot d\vec{S}' - \int_V \nabla \Phi \cdot \nabla G dV'$$

$$= \oint_{\partial V} \Phi \nabla G \cdot d\vec{S}' - \oint_{\partial V} G \nabla \Phi \cdot d\vec{S}' + \underbrace{\int_V \nabla^2 \Phi G dV'}_{\int_V -\frac{\rho}{\epsilon_0} G dV'}$$

$$\Rightarrow \Phi(\vec{x}) = \frac{1}{4\pi\epsilon_0} \int_V \rho(\vec{r}') G(\vec{r}, \vec{r}') dV'$$

$$+ \frac{1}{4\pi} \left[\oint_{\partial V} G(\vec{x}, \vec{x}') \nabla \Phi(\vec{x}') \cdot d\vec{S}' - \oint_{\partial V} \Phi(\vec{x}') \nabla G(\vec{x}, \vec{x}') \cdot d\vec{S}' \right]$$

V_0, V_1 :
 $G(\vec{r}, \vec{r}') = \frac{1}{|\vec{r} - \vec{r}'|}$, take plane as xy-plane

$$\Phi(\vec{r}) = -\frac{1}{4\pi} \int_{S_0} \Phi(\vec{r}') \nabla' G(\vec{r}, \vec{r}') \cdot d\vec{S}'$$

$$\nabla' G = \sum_i \partial_{x'_i} \frac{1}{(\sum_j (x_j - x'_j)^2)^{3/2}} = -\frac{1}{2} \frac{-2(x_i - x'_i)}{|\vec{x} - \vec{x}'|^3} = \frac{\vec{x} - \vec{x}'}{|\vec{x} - \vec{x}'|^3}$$

$$\Phi(\vec{r}) = \frac{-V_0 z}{4\pi} \int_{S_0} \frac{ds'}{|\vec{x} - \vec{x}'|^3} - \frac{V_1 z}{4\pi} \int_{S_1} \frac{ds'}{|\vec{x} - \vec{x}'|^3}$$

$S_0 = \text{plane}$
 $S_1 = \text{hole}$

W_0, W_1 :

$$\Phi(\vec{r}) = \frac{1}{4\pi} \int_{S_0} \frac{\nabla \Phi \cdot d\vec{S}'}{|\vec{x} - \vec{x}'|} = \frac{W_0}{4\pi} \int_{S_0} \frac{ds'}{|\vec{x} - \vec{x}'|} + \frac{W_1}{4\pi} \int_{S_1} \frac{ds'}{|\vec{x} - \vec{x}'|}$$

EMI-2 $\nabla \times \vec{H} = \frac{\partial \vec{B}}{\partial t} = 0 \Rightarrow \vec{H} = -\nabla \Phi_M$

$$\nabla \cdot \vec{B} = \nabla \cdot (\mu \vec{H}) = \nabla \cdot \mu \vec{H} + \mu \nabla \cdot \vec{H} = -\nabla \cdot \nabla \Phi_M - \mu \nabla^2 \Phi_M = 0$$

$$\nabla \cdot \nabla \Phi_M + \mu \nabla^2 \Phi_M = 0$$

$$\nabla \cdot \vec{B} = \mu_0 \nabla \cdot (\vec{H} + \vec{M}) = \mu_0 \nabla \cdot \vec{H} + \mu_0 \nabla \cdot \vec{M} = 0$$

$$\Rightarrow \nabla^2 \Phi_M = \nabla \cdot \vec{M}$$

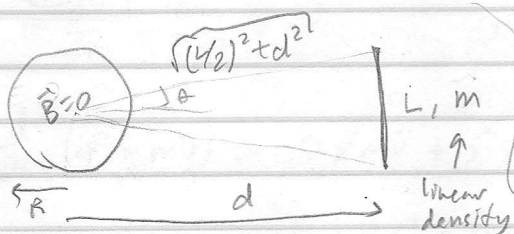
$$\vec{J} = -\frac{1}{\mu_0 \lambda_L} \hat{z}, \quad \nabla \times \vec{H} = \vec{J}, \quad \nabla \cdot \vec{B} = 0 \Rightarrow \vec{B} = \nabla \times \vec{A}$$

$$\vec{B} = -\mu_0 \lambda_L^2 \nabla \times \vec{J} = -\mu_0 \lambda_L^2 \nabla \times (\nabla \times \vec{A}) = -\mu_0 \lambda_L^2 (\nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A})$$

$$\nabla(\nabla \cdot \vec{A}) - (\nabla \cdot \nabla) \vec{A}$$

$$\mu \text{ constant (homogeneous)} \Rightarrow \nabla \cdot \vec{H} = \frac{1}{\mu} \nabla \cdot \vec{B} = 0 \Rightarrow$$

$$\vec{B} = +\mu_0 \lambda_L^2 \frac{1}{\mu} \nabla^2 \vec{B} = \frac{\mu_0}{\mu} \lambda_L^2 \nabla^2 \vec{B} \Rightarrow \lambda_L \sqrt{\frac{\mu_0}{\mu}} \text{ is penetration length}$$



$$\vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M} \Rightarrow \nabla \cdot \vec{H} = -\nabla \cdot \vec{M}$$

$$\nabla^2 \vec{H} = \frac{1}{\mu_0} \nabla^2 \vec{B} - \nabla^2 \vec{M}$$

$$\Rightarrow \vec{B} = \lambda_L^2 (\nabla^2 \vec{B} - \mu_0 \nabla^2 \vec{M} + \mu_0 \nabla(\nabla \cdot \vec{M}))$$

pick origin at center of sphere.

$$\vec{M}(\vec{x}) = \begin{cases} m \delta(x-d) \delta(y) \hat{z}, & z \in [R, R] \\ 0 & \text{otherwise} \end{cases}$$

$$= m \delta(x-d) \delta(y) [\theta(z+R) - \theta(z-R)] \hat{z}$$

equivalent to two monopoles of charge $q_m = \pm \frac{m}{L}$ at $x=d, z = \pm \frac{L}{2}$

$$\Rightarrow \text{image charges at } r = \frac{R^2}{\sqrt{(\frac{L}{2})^2 + d^2}}, \quad \theta = \pm \tan^{-1}\left(\frac{L}{2d}\right)$$

$$\cos \theta = \frac{d}{\sqrt{d^2 + (\frac{L}{2})^2}} \quad \sin \theta = \frac{\pm \frac{L}{2}}{\sqrt{d^2 + (\frac{L}{2})^2}}$$

$$\Rightarrow x = r \cos \theta = \frac{R^2 d}{d^2 + (\frac{L}{2})^2}, \quad z = \pm \frac{R^2 L/2}{d^2 + (\frac{L}{2})^2}$$

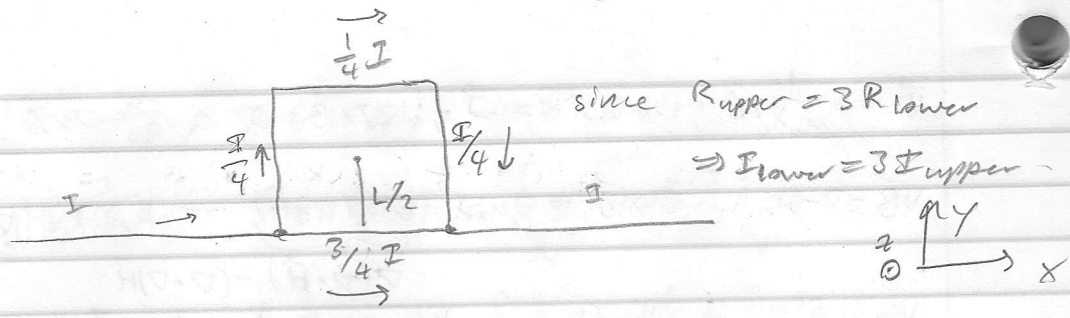
$$q'_m = \mp \frac{R}{r} q_m = \mp \frac{\sqrt{d^2 + (\frac{L}{2})^2}}{R} \frac{m}{L}$$

$$\Phi_M(\vec{x}) = \sum \frac{q_m}{4\pi |x-x'|} = \frac{1}{4\pi} \frac{m}{L} \left[\frac{1}{\sqrt{(x-d)^2 + (z-\frac{L}{2})^2 + y^2}} - \frac{1}{\sqrt{(x-d)^2 + (z+\frac{L}{2})^2 + y^2}} \right]$$

$$+ \frac{\sqrt{d^2 + (\frac{L}{2})^2}}{R} \left(\frac{-1}{\sqrt{(x-x')^2 + (z-z')^2 + y^2}} + \frac{1}{\sqrt{(x-x')^2 + (z+z')^2 + y^2}} \right)$$

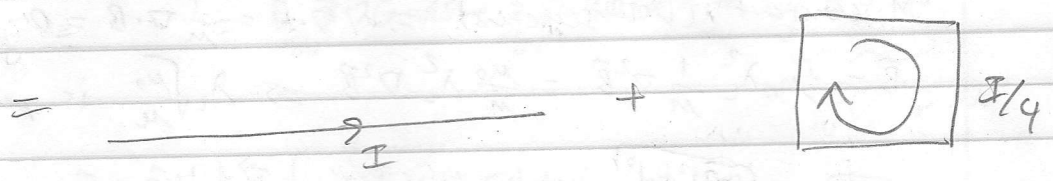
$$x' = \frac{R^2 d}{d^2 + (\frac{L}{2})^2} \quad z' = \frac{R^2 L/2}{d^2 + (\frac{L}{2})^2}$$

013 EMI-3



since $R_{upper} = 3R_{lower}$

$\Rightarrow I_{lower} = 3I_{upper}$



$$\vec{B}_{line} = \frac{\mu_0 I}{2\pi(L/2)} \hat{z}$$

$$\vec{B}_{loop} = 4 \vec{B}_{segment}$$

$$\vec{B}_{segment} = \frac{\mu_0}{4\pi} \int_{-L/2}^{L/2} \frac{-\frac{I}{4} d\vec{x} \times (\vec{x} \hat{x} + \frac{L}{2} \hat{y})}{(x^2 + (\frac{L}{2})^2)^{3/2}} = -\frac{I}{4} \frac{L}{2} \hat{z} \int_{-L/2}^{L/2} \frac{dx}{(x^2 + (\frac{L}{2})^2)^{3/2}}$$

$$\tan \theta = \frac{z}{x} \Rightarrow dx = \frac{L}{2} \sec^2 \theta d\theta$$

$$\vec{B}_{loop} = -\frac{\mu_0 I L}{4\pi} \frac{\hat{z}}{2} \left(\frac{2}{L}\right)^2 \int_{-\pi/4}^{\pi/4} \frac{\sec^2 \theta d\theta}{\sec^3 \theta}$$

$$= -\frac{\mu_0}{4\pi} \sqrt{2} \frac{I \hat{z}}{(L/2)}$$

$$\int \cos \theta d\theta = \sin \theta \Big|_{-\pi/4}^{\pi/4} = \sqrt{2}$$

$$\Rightarrow \vec{B} = \frac{\mu_0 I \hat{z}}{\pi L} \left(1 - \frac{\sqrt{2}}{2}\right)$$

EMI-5

$$\int_V \nabla \cdot \vec{B} dV = \int_V 4\pi \delta(\vec{r}) = 4\pi$$

but $\nabla \cdot \vec{B} = \nabla \cdot (\nabla \times \vec{A}) = 0 \Rightarrow \int_V \nabla \cdot \vec{B} = 0$

\Rightarrow cannot have $\nabla \times \vec{A} = \vec{B}$ everywhere

$$\vec{B} = \nabla \times \vec{A} + C \delta(x) \delta(y) \theta(z) \hat{z}$$

$$\nabla \cdot \vec{B} = C \delta(x) \delta(y) \partial_z \theta(z) = C \delta(x) \delta(y) \delta(z) = 4\pi \delta(\vec{r})$$

$$\Rightarrow C = 4\pi$$

• g $\xrightarrow{m, e} \vec{v}$ $m \frac{d\vec{v}}{dt} = \frac{e}{c} \vec{v} \times \vec{B}$, $\vec{B} = \nabla \times \vec{A} + 4\pi \delta(x) \delta(y) \theta(z) \hat{z}$
 $= \frac{g}{r^2} \hat{r}$

$$m \frac{d\vec{v}}{dt} = \frac{eg}{cr^2} \vec{v} \times \hat{r}, \quad (r, \theta, \phi) \text{ spherical coords}$$

$$\frac{d}{dt} (\vec{r} \times m\vec{v}) = \vec{v} \times m\vec{v} + \vec{r} \times m \frac{d\vec{v}}{dt} = \frac{eg}{cr^3} \vec{r} \times (\vec{v} \times \vec{r})$$

$$= \frac{eg}{cr^3} (\vec{v} r^2 - \vec{r} (\vec{v} \cdot \vec{r})) = \frac{eg}{c} \left(\frac{\vec{v}}{r} - \frac{\vec{r} (\vec{v} \cdot \vec{r})}{r^3} \right)$$

but $\frac{d}{dt} \left(\frac{\vec{r}}{r} \right) = \frac{\vec{v}}{r} - \frac{\vec{r} v_r}{r^2} \Rightarrow \frac{d}{dt} (\vec{r} \times m\vec{v}) = \frac{eg}{c} \frac{d}{dt} \left(\frac{\vec{r}}{r} \right)$

$$\Rightarrow \frac{d\vec{J}}{dt} = 0, \quad \vec{J} = \vec{r} \times m\vec{v} - \frac{eg}{c} \frac{\vec{r}}{r}$$

\vec{J} quantized in \hbar , take straight line path $\nabla \times \vec{r} = 0$

$$\Rightarrow m \frac{d\vec{v}}{dt} = 0.$$

$$\vec{J} = -\frac{eg}{c} \frac{\vec{r}}{r} \Rightarrow J_r = -\frac{eg}{c} = n\hbar, \quad n \in \mathbb{Z}$$

$$\Rightarrow \frac{eg}{c} = n\hbar, \quad n \in \mathbb{Z}$$

EM1-4 use image charges

2013 QM1-1 $[J_i, A_j] = i\hbar \epsilon_{ijk} A_k$

$$\begin{aligned}
 [J_i, A_j B_j] &= J_i A_j B_j - A_j B_j J_i \\
 &= [J_i, A_j] B_j + A_j [J_i, B_j] \\
 &= -i\hbar \epsilon_{ijk} A_k B_j + i\hbar \epsilon_{ijk} A_j B_k = -i\hbar \epsilon_{ijk} (\underbrace{A_k B_j}_{\text{anti sym}} + \underbrace{A_j B_k}_{\text{sym}}) \\
 &= 0
 \end{aligned}$$

$\Rightarrow A_j B_j = \vec{A} \cdot \vec{B}$ scalar

$$\begin{aligned}
 [J_i, \epsilon_{jkl} A_k B_l] &= \epsilon_{jkl} (J_i A_k B_l - A_k B_l J_i) \\
 &= \epsilon_{jkl} ([J_i, A_k] B_l + A_k [J_i, B_l]) \\
 &= \epsilon_{jkl} (-i\hbar \epsilon_{ikm} A_m B_l - i\hbar \epsilon_{ilm} A_k B_m) \\
 &= i\hbar \epsilon_{jkl} (\epsilon_{ikm} A_m B_l + \epsilon_{ilm} A_k B_m) \\
 &= i\hbar (\underbrace{\epsilon_{kls} \epsilon_{kmi}}_{\delta_{lm} \delta_{si} - \delta_{li} \delta_{sm}} A_m B_l + \underbrace{\epsilon_{ljk} \epsilon_{lmi}}_{\delta_{jm} \delta_{ki} - \delta_{ji} \delta_{km}} A_k B_m) \\
 &= i\hbar (A_j B_i \delta_{ij} - A_j B_i + A_i B_j - A_k B_k \delta_{ij}) \\
 &= i\hbar (\underbrace{\delta_{ik} \delta_{ls} - \delta_{il} \delta_{ks}}_{\epsilon_{ijm} \epsilon_{mkl}}) A_k B_l = i\hbar \epsilon_{ijk} (\vec{A} \times \vec{B})_k
 \end{aligned}$$

QM1-2 $\oint p dx = nh$, $p = \sqrt{2m(E-V)}$

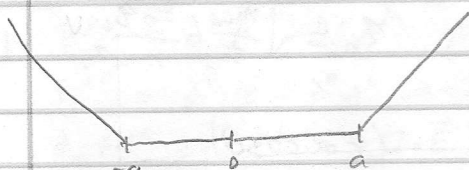
$$\int_{x_1}^{x_2} \sqrt{2m(E-V(x))} dx = (n + \frac{1}{2}) \pi \hbar$$

$$\int_{x_1}^{x_2} \sqrt{2m(E - \alpha x^4)} dx = \sqrt{2mE} \int_{x_1}^{x_2} \sqrt{1 - \frac{\alpha}{E} x^4} dx, \quad y = \left(\frac{\alpha}{E}\right)^{1/4} x$$

$$(n + \frac{1}{2}) \pi \hbar = \sqrt{2mE} \left(\frac{E}{\alpha}\right)^{1/4} 2 \int_0^1 \sqrt{1-y^4} dy, \quad \int_0^1 \sqrt{1-y^4} dy \equiv I$$

$$\left(\frac{4m^2}{\alpha}\right)^{1/4} E^{3/4} 2I = (n + \frac{1}{2}) \pi \hbar$$

$$E = \left(\frac{\alpha}{4m^2}\right)^{1/3} \left[\frac{(n + \frac{1}{2}) \pi \hbar}{2I}\right]^{4/3} \quad \text{where } I = \frac{\Gamma(1/4) \Gamma(3/2)}{4 \Gamma(7/4)}$$



$$\begin{aligned}
 (n+\frac{1}{2})\pi\hbar &= 2 \int_0^a dx \sqrt{2m(E-V(x))} \\
 &= 2a\sqrt{2mE} + 2 \int_0^{x_2} \sqrt{2m(E-k(x-a))} dx \\
 &= 2\sqrt{2mE} \left[a + \int_0^{y_2=x_2-a} \sqrt{1-\frac{k}{E}y} dy \right] \rightarrow \frac{2}{3} \left(1-\frac{k}{E}y\right)^{3/2} \Big|_0^{y_2} \\
 &= 2\sqrt{2mE} \left[a - \frac{2E}{3k} \left(1-\frac{k}{E}y\right)^{3/2} \Big|_0^{y_2} \right], \quad \frac{k}{E}y_2 = 1 \\
 &= 2\sqrt{2mE} \left[a + \frac{2E}{3k} \right] = (n+\frac{1}{2})\pi\hbar
 \end{aligned}$$

QM1-3 $V'(x) = \frac{1}{2}m\omega^2 x^2 - E_0 q x = \frac{1}{2}m\omega^2 \left(x^2 - \frac{2E_0 q}{m\omega^2} x + \left(\frac{E_0 q}{m\omega^2}\right)^2 \right) + \text{const}$

$$= \frac{1}{2}m\omega^2 \left(x - \frac{E_0 q}{m\omega^2} \right)^2 + \text{const}$$

$t < 0: x' = x - \frac{E_0 q}{m\omega^2} \quad \xi' = \xi - \frac{\sqrt{m\omega} E_0 q}{\hbar m\omega^2}$

$$\xi_0 = \frac{E_0 q}{m\omega^2}$$

$$\psi(x) = \left(\frac{m\omega}{\pi\hbar}\right)^{1/4} e^{-(\xi-\xi_0)^2/2} \rightarrow e^{-\frac{\xi^2 - 2\xi\xi_0 + \xi_0^2}{2}}$$

$t \geq 0:$

$$\int dx \psi(x) \psi_n(x) = \sqrt{\frac{m\omega}{\pi\hbar}} \frac{1}{\sqrt{2^n n!}} \int H_n(\xi) e^{-\xi^2} e^{\xi\xi_0 - \xi_0^2/2} dx$$

$2\xi = \xi_0 \quad e^{-\xi^2} = e^{-\xi_0^2/4}$

$$= \sqrt{\frac{m\omega}{\pi\hbar}} \frac{1}{\sqrt{2^n n!}} \int H_n(\xi) e^{-\xi^2} e^{2\xi\xi_0 - \xi^2} e^{-\xi_0^2/4} dx$$

$$= \sqrt{\frac{m\omega}{\pi\hbar}} \frac{e^{-\xi_0^2/4}}{\sqrt{2^n n!}} \int H_n(\xi) \sum_{k=0}^{\infty} \frac{\xi^k}{k!} H_k(\xi) e^{-\xi^2} \sqrt{\frac{\hbar}{m\omega}} d\xi$$

$$= \frac{e^{-\xi_0^2/4}}{\sqrt{2^n n! \pi}} \sum_{k=0}^{\infty} \frac{(\xi_0/2)^k}{k!} \int H_n(\xi) H_k(\xi) e^{-\xi^2} d\xi \quad \sqrt{\pi} 2^n n! \delta_{nk}$$

note $\int |\psi_n(x)|^2 dx = \frac{1}{\sqrt{\pi} 2^n n!} \int H_n(\xi) H_n(\xi) e^{-\xi^2} d\xi = 1$

$$\Rightarrow = \sqrt{\pi} 2^n n!$$

2013

$$P_n = \left(e^{-\frac{3}{2}} \sqrt{\frac{2^n n!}{n!}} \left(\frac{3}{2} \right)^{n/2} \right)^2, \quad \frac{3}{2} = \sqrt{\frac{m\omega}{\hbar}} \frac{E_0}{m\omega^2}$$

QM1-4 must have $\psi|_{z=0} = 0$ ($z \propto \cos\theta$)

$$P_l^m(-x) = (-1)^{l+m} P_l^m(x) \Rightarrow l+m \text{ must be odd}$$

\Rightarrow wavefunctions $Y_l^m(\theta, \phi)$ for $l+m$ odd

$$l=1: m=0 \quad l=3: m=0, \pm 2$$

$$l=2: m=\pm 1 \quad l=4: m=\pm 1, \pm 3$$

$$H = \frac{L^2}{2ma^2}, \quad \text{radius } a$$

$$H\psi = \frac{l(l+1)\hbar^2}{2ma^2} \psi \Rightarrow E_l = \frac{l(l+1)\hbar^2}{2ma^2}, \quad l=1, 2, \dots$$

l level is l -degenerate ($m = \pm 1, -1, \dots, l-1$)

QM1-5 $H = \omega S_z$, $|\alpha\rangle = a|+\rangle + b|-\rangle = \begin{pmatrix} a \\ b \end{pmatrix}$, $S_x = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$, $S_y = \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$

$$\langle S_x \rangle_0 = \frac{\hbar}{2} (a \ b) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \frac{\hbar}{2} (a \ b) \begin{pmatrix} b \\ a \end{pmatrix} = \frac{\hbar}{2} (2ab) = \hbar ab$$

$$\langle S_y \rangle_0 = \frac{\hbar}{2} (a \ b) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \frac{\hbar}{2} (a \ b) \begin{pmatrix} -ib \\ ia \end{pmatrix} = \frac{\hbar}{2} i(ab - ba) = 0$$

$$\langle S_y \rangle_t e^{iHt/\hbar} = \begin{pmatrix} e^{i\omega t/2} & \\ & e^{-i\omega t/2} \end{pmatrix}$$

$$\langle S_x \rangle_t = \frac{\hbar}{2} \begin{pmatrix} e^{i\omega t/2} & \\ & e^{-i\omega t/2} \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} e^{-i\omega t/2} \\ e^{i\omega t/2} \end{pmatrix}$$

$$= \frac{\hbar}{2} \begin{pmatrix} e^{i\omega t/2} & \\ & e^{-i\omega t/2} \end{pmatrix} \begin{pmatrix} 0 & e^{i\omega t/2} \\ e^{-i\omega t/2} & 0 \end{pmatrix} = \frac{\hbar}{2} \begin{pmatrix} 0 & e^{i\omega t} \\ e^{-i\omega t} & 0 \end{pmatrix}$$

$$= S_x|_0 \cos\omega t - S_y|_0 \sin\omega t$$

$$S_y|_t = \frac{\hbar}{2} \begin{pmatrix} e^{i\omega t/2} & \\ & e^{-i\omega t/2} \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} e^{-i\omega t/2} \\ e^{i\omega t/2} \end{pmatrix}$$

$$= \frac{\hbar}{2} \begin{pmatrix} e^{i\omega t/2} & \\ & e^{-i\omega t/2} \end{pmatrix} \begin{pmatrix} 0 & -ie^{i\omega t/2} \\ ie^{-i\omega t/2} & 0 \end{pmatrix} = \frac{\hbar}{2} \begin{pmatrix} 0 & -ie^{i\omega t} \\ ie^{-i\omega t} & 0 \end{pmatrix}$$

$$= S_y|_0 \cos\omega t + S_x|_0 \sin\omega t \Rightarrow \text{same for exp values}$$

$$g = \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix} \quad A^\mu = (\Phi, \vec{A}) \quad j^\mu = (\rho, \vec{j})$$

$$\text{EMII-1} \quad F^{\mu\nu} = \partial^\mu A^\nu - \partial^\nu A^\mu \Rightarrow d_\mu F^{\mu\nu} = d_\mu d^\mu A^\nu - \partial^\nu d_\mu A^\mu$$

$$F^{i0} = \partial^i \Phi - \partial^0 A^i = -\nabla \Phi - \partial \vec{A} / \partial t = \vec{E}^i, \quad F^{0i} = -E^i$$

$$d_\mu F^{\mu 0} = -\partial_i E^i = -\nabla \cdot \vec{E}$$

$$\partial_i F^{ij} = \partial_i \partial^i A^j - \partial^j \partial_i A^i = -\nabla^2 A^j - \partial^j \nabla \cdot \vec{A} = -(\nabla^2 \vec{A} - \nabla(\nabla \cdot \vec{A}))_j$$

$$\vec{E} \times \vec{B} = (\nabla \times (\nabla \times \vec{A}))_j = -(\nabla \times \vec{B})_j, \quad \partial_0 F^{0j} = -\partial_0 E^j$$

$$\text{so } d_\mu F^{\mu\nu} = j^\nu \Leftrightarrow \nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}, \quad \nabla \times \vec{B} - \frac{\partial \vec{E}}{\partial t} = \mu_0 \vec{j}$$

dual tensor $F^{\alpha\beta}$: $\begin{matrix} \vec{E} \rightarrow \vec{B} \\ \vec{B} \rightarrow -\vec{E} \end{matrix}$

$$\text{then } d_\mu F^{\mu\nu} = 0 \Leftrightarrow \nabla \cdot \vec{B} = 0, \quad \nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$$

Equations are valid in any frame (with E, ρ transformed by Lorentz transformation)

$$\vec{E} \cdot \vec{B} = 0$$

$$E^i = F^{i0}$$

$$B^i = F^{i0}$$

$$\begin{pmatrix} \gamma & \gamma\beta \\ \gamma\beta & \gamma \end{pmatrix} \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -B_z & B_y \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{pmatrix} \begin{pmatrix} \gamma & \gamma\beta \\ \gamma\beta & \gamma \\ & & 1 & \\ & & & 1 \end{pmatrix} = \begin{pmatrix} \dots \\ \dots \\ \dots \\ \dots \end{pmatrix} \begin{pmatrix} -\gamma\beta E_x - \gamma E_x & -E_y & -E_z \\ \gamma E_x & \gamma\beta E_y & -B_z & B_y \\ \gamma\beta E_y + \gamma B_z & \gamma\beta E_y + \gamma B_z & 0 & -B_x \\ \gamma E_z - \gamma\beta B_y & \gamma\beta E_z - \gamma B_y & B_x & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & & & \dots \\ \gamma^2(1-\beta^2)E_x & 0 & & \\ \gamma E_y + \gamma\beta B_z & \gamma\beta E_y + \gamma B_z & 0 & \\ \gamma E_z - \gamma\beta B_y & \gamma\beta E_z - \gamma B_y & B_x & 0 \end{pmatrix}$$

$$E'_x = E_x, \quad E'_y = \gamma(E_y + \beta B_z), \quad E'_z = \gamma(E_z - \beta B_y)$$

$$B'_x = B_x, \quad B'_y = \gamma(B_y - \beta E_z), \quad B'_z = \gamma(B_z + \beta E_y)$$

$$\begin{aligned} \vec{E}' \cdot \vec{B}' &= E_x B_x + \gamma^2 (E_y B_y - \beta^2 E_z B_z + \beta (B_z B_y - E_z E_y)) \\ &\quad + \gamma^2 (E_z B_z - \beta^2 E_y B_y + \beta (E_y E_z - B_y B_z)) \\ &= E_x B_x + E_y B_y + E_z B_z = \vec{E} \cdot \vec{B} \end{aligned}$$

$$\text{pure electric: } \vec{B} = 0 \Rightarrow \vec{E}' = (\gamma E_x, \gamma E_y, \gamma E_z)$$

$$\text{so } \vec{E}' = 0 \Rightarrow \vec{E} = 0 \quad (\Rightarrow \vec{B}' = 0) \quad \text{since } \gamma \neq 0$$

$$\text{ii) } \begin{pmatrix} \gamma & \gamma\beta & & \\ \gamma\beta & \gamma & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -B_z & B_y \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{pmatrix} \begin{pmatrix} \gamma & \gamma\beta & & \\ \gamma\beta & \gamma & & \\ & & 1 & \\ & & & 1 \end{pmatrix} = \begin{pmatrix} \dots \\ \dots \\ \dots \\ \dots \end{pmatrix} \begin{pmatrix} -\gamma\beta E_x - \gamma E_x & -E_y & -E_z \\ \gamma E_x & \gamma\beta E_y & -B_z & B_y \\ \gamma\beta E_y + \gamma B_z & \gamma\beta E_y + \gamma B_z & 0 & -B_x \\ \gamma E_z - \gamma\beta B_y & \gamma\beta E_z - \gamma B_y & B_x & 0 \end{pmatrix} = \vec{E}' \cdot \vec{B}' = E_x B_x + E_y B_y + E_z B_z = 0$$

2013

EMU-2

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} = -i\omega \vec{B}, \quad \nabla \times \vec{B} = \mu \epsilon \frac{\partial \vec{E}}{\partial t}, \quad \nabla \cdot \vec{E} = \nabla \cdot \vec{B} = 0$$

$$\begin{aligned} \nabla \times (\nabla \times \vec{E}) &= i\omega \nabla \times \vec{B} = \mu \epsilon \omega^2 \vec{E} = -\mu \epsilon \omega^2 \vec{E} \\ &= -\nabla (\nabla \cdot \vec{E}) - \nabla^2 \vec{E} \Rightarrow (\nabla^2 + \mu \epsilon \omega^2) \vec{E} = 0 \end{aligned}$$

$$\begin{aligned} \nabla \times (\nabla \times \vec{B}) &= -i\omega \mu \epsilon \nabla \times \vec{E} = \omega^2 \mu \epsilon \vec{B} \\ &= \nabla (\nabla \cdot \vec{B}) - \nabla^2 \vec{B} \Rightarrow (\nabla^2 + \mu \epsilon \omega^2) \vec{B} = 0 \end{aligned}$$

$$\vec{E} = \hat{E}_t(x, y) f(z)$$

$$\nabla^2 \vec{E} = f \nabla_t^2 \vec{E}_t + \vec{E}_t \frac{\partial^2 f}{\partial z^2} = -\mu \epsilon \omega^2 \vec{E}_t f$$

$$\nabla_t^2 \vec{E}_t + \vec{E}_t \left(\frac{\partial^2 f}{\partial z^2} + \mu \epsilon \omega^2 \right) = 0$$

function of z , must be constant

$$\Rightarrow \frac{\partial^2 f}{\partial z^2} = (-\mu \epsilon \omega^2 + \text{const}) f$$

call this $-k^2$

$$\Rightarrow \frac{\partial^2}{\partial z^2} \vec{E} = -k^2 \vec{E} \quad (\text{must be } - \text{ so doesn't go to } \infty)$$

$$\text{so } (\nabla_t^2 + \mu \epsilon \omega^2 - k^2) \vec{E} = 0, \quad \text{likewise for } \vec{B}$$

$$\nabla \cdot \vec{E} = \nabla_t \cdot \vec{E}_t + \partial_z E_z = 0 \quad \text{likewise } \vec{B}$$

$$\nabla \times \vec{E} = i\omega \vec{B} \Rightarrow \hat{z} \cdot \nabla_t \times \vec{E}_t = i\omega B_z$$

$$\begin{aligned} \hat{z} \times (\nabla \times \vec{E}) &= \nabla (\hat{z} \cdot \vec{E}) - (\hat{z} \cdot \nabla) \vec{E} = \nabla E_z - \frac{\partial}{\partial z} (\vec{E}_t + E_z \hat{z}) \\ &= \nabla_t \vec{E}_t - \frac{\partial \vec{E}_t}{\partial z} \quad \frac{\partial E_z}{\partial z} \hat{z} + \nabla_t E_z \end{aligned}$$

$$\Rightarrow \nabla_t E_z - \frac{\partial \vec{E}_t}{\partial z} = i\omega \hat{z} \times \vec{B}_t$$

$$\nabla \times \vec{B} = -i\omega \mu \epsilon \vec{E} \Rightarrow \hat{z} \cdot \nabla_t \times \vec{B}_t = -i\omega \mu \epsilon E_z$$

$$\nabla_t B_z - \frac{\partial \vec{B}_t}{\partial z} = -i\omega \mu \epsilon \hat{z} \times \vec{E}_t$$

$$\uparrow$$

$$ik \vec{B}_t$$

$$\begin{aligned} \nabla_t E_z &= -ik \hat{E}_t + i\omega \hat{z} \times \hat{B}_t & \Rightarrow \hat{E}_t &= \frac{1}{ik} (\nabla_t E_z - i\omega \hat{z} \times \hat{B}_t) \\ \nabla_t B_z &= ik \hat{B}_t - i\mu\epsilon\omega \hat{z} \times \hat{E}_t & \Rightarrow \hat{B}_t &= \frac{1}{ik} (\nabla_t B_z + i\mu\epsilon\omega \hat{z} \times \hat{E}_t) \end{aligned}$$

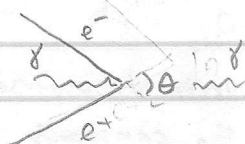
$$\hat{E}_t = \frac{1}{ik} \nabla_t E_z - \frac{\omega}{ik^2} (\hat{z} \times \nabla_t B_z - i\mu\epsilon\omega \hat{E}_t)$$

$$\hat{E}_t = \frac{1}{ik} \nabla_t E_z - \frac{\omega}{ik} \hat{z} \times \nabla_t B_z + \mu\epsilon \frac{\omega^2}{k^2} \hat{E}_t$$

$$\Rightarrow \hat{E}_t = \frac{\nabla_t E_z - \omega \hat{z} \times \nabla_t B_z}{ik(1 - \mu\epsilon \frac{\omega^2}{k^2})} = \frac{i}{\mu\epsilon\omega^2 - k^2} (k \nabla_t E_z - \omega \hat{z} \times \nabla_t B_z)$$

$$\begin{aligned} \Rightarrow \hat{B}_t &= \frac{1}{ik} (\nabla_t B_z + i\mu\epsilon\omega \frac{i}{\mu\epsilon\omega^2 - k^2} (k \hat{z} \times \nabla_t E_z + \omega \nabla_t B_z)) \\ &= \frac{i}{\mu\epsilon\omega^2 - k^2} \left(\frac{\mu\epsilon\omega^2 - k^2}{-k} \nabla_t B_z + \mu\epsilon\omega \hat{z} \times \nabla_t E_z + \frac{\mu\epsilon\omega^2}{k} \nabla_t B_z \right) \\ &= \frac{i}{\mu\epsilon\omega^2 - k^2} (k \nabla_t B_z + \mu\epsilon\omega \hat{z} \times \nabla_t E_z) \end{aligned}$$

EM11-3 lab frame



$$E_e = \gamma m_e \quad \gamma^2 m_e^2 = p_e^2 + m_e^2$$

$$p_e = m_e \sqrt{\gamma^2 - 1}$$

$$p_{ex} = p_e \cos(\theta/2) \quad (\gamma v E = p)$$

$$E_1 - E_2 = 2m_e \sqrt{\gamma^2 - 1} \cos(\theta/2) \quad \Rightarrow \quad E_1 = m_e (\gamma + \sqrt{\gamma^2 - 1} \cos(\theta/2))$$

$$E_1 + E_2 = 2\gamma m_e \quad E_2 = m_e (\gamma - \sqrt{\gamma^2 - 1} \cos(\theta/2))$$

$$\gamma \gg 1: \sqrt{\gamma^2 - 1} = \gamma(1 - \gamma^{-2})^{1/2} \approx \gamma(1 - \frac{1}{2}\gamma^{-2}) = \gamma - \frac{1}{2}\gamma^{-1}$$

$$\theta \rightarrow 0 \Rightarrow E_1 \approx 2\gamma m_e - \frac{m_e}{2\gamma}$$

$$E_2 \approx \frac{m_e}{2\gamma}$$

2013

EMII-4

$$\nabla \cdot \vec{D} = 0, \quad \vec{D} = \epsilon_0 \vec{E} + \vec{P} = \epsilon_0 \vec{E} + \gamma \nabla \times \vec{E}$$

$$\Rightarrow \nabla \cdot \vec{D} = \nabla \cdot (\epsilon_0 \vec{E} + \gamma \nabla \times \vec{E}) = \epsilon_0 \nabla \cdot \vec{E} = 0 \Rightarrow \nabla \cdot \vec{E} = 0$$

$$\nabla \times \vec{H} = \frac{1}{\mu_0} \nabla \times \vec{B} = \frac{\partial \vec{D}}{\partial t} = \epsilon_0 \frac{\partial \vec{E}}{\partial t} + \gamma \nabla \times \left(\frac{\partial \vec{E}}{\partial t} \right)$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \Rightarrow \nabla \times (\nabla \times \vec{E}) = -\frac{\partial}{\partial t} \left(\mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} + \mu_0 \gamma \nabla \times \frac{\partial \vec{E}}{\partial t} \right)$$

$$\nabla^2 \vec{E} = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \left(\vec{E} + \frac{\gamma}{\epsilon_0} \nabla \times \vec{E} \right)$$

$$\vec{E} = \vec{E}_0 e^{i(kz - \omega t)}, \quad \nabla \times \vec{E} = \hat{x}(\partial_y E_z - ik E_{yz}) + \hat{y}(ik E_x - \partial_x E_z)$$

$$(-k^2 + \nabla_t^2) \vec{E}_0 = \frac{-\omega^2}{c^2} \left(\vec{E}_0 + \frac{\gamma}{\epsilon_0} (ik \hat{x} \times \vec{E}_0 + \nabla \times \vec{E}_0) \right) + \frac{\omega^2}{c^2} (\partial_x E_y - \partial_y E_x)$$

transverse modes: all vectors point transversely except $\nabla \times \vec{E}_0$,

$$\text{so } \nabla \times \vec{E}_0 = 0$$

$$\left(\nabla_t^2 + \frac{\omega^2}{c^2} - k^2 \right) \vec{E}_0 = -\frac{\omega^2 \gamma}{c^2 \epsilon_0} ik \hat{z} \times \vec{E}_0$$

longitudinal modes: $\vec{E}_0 = E_0 \hat{z}$; $\hat{z} \times \vec{E}_0 = 0$,

$$\nabla \times \vec{E}_0 = \hat{x} \partial_y E_0 - \hat{y} \partial_x E_0 = 0, \quad \text{only transverse terms}$$

$$\Rightarrow \partial_y E_0 = \partial_x E_0 = 0 \Rightarrow E_0(x, y) = E_0 \text{ constant}$$

$$\Rightarrow \left(\frac{\omega^2}{c^2} - k^2 \right) E_0 = 0$$

\Rightarrow only longitudinal modes are pure plane waves
(no transverse variations) with $\omega = ck$

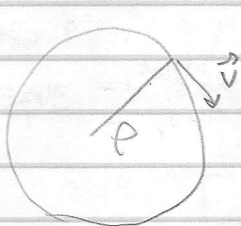
EM11-5 $ds^2 = -dt^2 + dr^2$, $d\tau^2 = -ds^2 = dt^2 - dr^2$ ($dr^2 = dx^2 + dy^2 + dz^2$)

$$d\tau^2 = dt^2 - \frac{dr^2}{dt^2} dt^2 = dt^2(1 - \beta^2) \Rightarrow d\tau = dt \sqrt{1 - \beta^2} = \frac{dt}{\gamma}$$

$$v^\alpha = \frac{dx^\alpha}{d\tau} = \left(\frac{dt}{d\tau}, \frac{d\vec{r}}{d\tau} \right), \text{ but } \frac{dt}{d\tau} = \gamma, \frac{d\vec{r}}{d\tau} = \frac{d\vec{r}}{dt} \frac{dt}{d\tau} = \gamma \vec{v}$$

$$= (\gamma, \gamma \vec{v})$$

$$\eta = \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix}$$



$$\frac{d\vec{v}}{dt} = \frac{v^2}{\rho} \quad P = \frac{2e^2}{3c^3} \frac{d\vec{v}}{dt} \cdot \frac{d\vec{v}}{dt}$$

$$\rightarrow P = \frac{2e^2}{3c^3} \frac{dv^\alpha}{dt} \frac{dv_\alpha}{d\tau}$$

since $-\frac{dv^\alpha}{d\tau} \frac{dv_\alpha}{d\tau} = \left| \frac{d(\gamma \vec{v})}{d\tau} \right|^2 - \left| \frac{d\gamma}{d\tau} \right|^2$, $\frac{d\gamma}{dv} = \frac{\gamma^3 v}{c^2}$

$$= \left| \frac{d(\gamma \vec{v})}{d\tau} \right|^2 - \left| \frac{\gamma^3 v}{c^2} \frac{dv}{d\tau} \right|^2$$

$\propto v^2 \rightarrow 0$ for $v \ll c$

$$\frac{d(\gamma \vec{v})}{d\tau} = \gamma^3 v \frac{dv}{d\tau} + \gamma \frac{d\vec{v}}{d\tau}$$

but $\frac{dv}{d\tau} = 0$ for circular motion

$$\Rightarrow P = \frac{2e^2}{3c^3} \left| \gamma \frac{d\vec{v}}{d\tau} \right|^2, \quad \frac{d\vec{v}}{d\tau} = \frac{d\vec{v}}{dt} \frac{dt}{d\tau} = \gamma \frac{d\vec{v}}{dt}$$

$$\Rightarrow P = \frac{2e^2}{3c^3} \gamma^4 \left| \frac{d\vec{v}}{dt} \right|^2 = \frac{2e^2}{3c^3} \gamma^4 \frac{v^4}{\rho^2} = \frac{2e^2 c}{3\rho^2} \beta^4 \gamma^4$$

General: $P = \frac{2e^2}{3c^3} \left(\left| \frac{d(\gamma \vec{v})}{d\tau} \right|^2 - \left| \frac{d\gamma}{d\tau} \right|^2 \right)$

$$\vec{\alpha} = \gamma^4 v \frac{dv}{d\tau} + \gamma^2 \frac{d\vec{v}}{d\tau} = \gamma^4 \beta \dot{\beta} \vec{v} + \gamma^2 \ddot{\vec{v}}$$

$$\alpha_0 = -v \gamma^3 \frac{dv}{d\tau} = -\gamma^4 \beta \dot{\beta}$$

2013

QM11-1

$$H = \frac{p_z^2}{2m} + k_1 x^2 + k_2 y^2, \quad L_z = x p_y - y p_x$$

$$[p_z^2, L_z] = [p_x^2, x] p_y - [p_y^2, y] p_x = -i\hbar(2p_x p_y - 2p_y p_x) = 0$$

$$[x^2, L_z] = \hbar y [x^2, p_x] = -y i\hbar 2x$$

$$[y^2, L_z] = x [y^2, p_y] = x i\hbar 2y$$

$$[H, L_z] = i\hbar(-2xyk_1 + 2xyk_2) = 2i\hbar xy(k_2 - k_1)$$

$$L_z \text{ conserved} \Leftrightarrow k_1 = k_2$$

QM11-2

$$c_1(0) = 1, \quad c_2(0) = 0 \quad V_{12} = \gamma e^{i\omega t}, \quad V_{21} = \gamma e^{-i\omega t} \quad \omega_{12} = -\omega_{21} = \frac{E_1 - E_2}{\hbar}$$

$$i\hbar \frac{dc_1}{dt} = V_{12} e^{i\omega_{21}t} c_2 = \gamma e^{i(\omega - \omega_{21})t} c_2$$

$$i\hbar \frac{dc_2}{dt} = \gamma e^{i(-\omega + \omega_{21})t} c_1$$

$$\frac{dc_1}{dt} = \frac{\gamma}{i\hbar} e^{i(\omega - \omega_{21})t} c_2, \quad \frac{dc_2}{dt} = \frac{\gamma}{i\hbar} e^{-i(\omega - \omega_{21})t} c_1$$

$$\frac{d^2 c_1}{dt^2} = \frac{\gamma}{\hbar} (\omega - \omega_{21}) \frac{i\hbar}{\gamma} \frac{dc_1}{dt} + \frac{\gamma}{i\hbar} e^{i(\omega - \omega_{21})t} \frac{dc_2}{dt}$$

$$\frac{d^2 c_1}{dt^2} = i(\omega - \omega_{21}) \frac{dc_1}{dt} - \left(\frac{\gamma}{\hbar}\right)^2 c_1$$

$$\text{try } c_1 \propto e^{ikt} \Rightarrow -k^2 = -k(\omega - \omega_{21}) - \left(\frac{\gamma}{\hbar}\right)^2$$

$$k^2 - (\omega - \omega_{21})k - \frac{\gamma^2}{\hbar^2} = 0 \Rightarrow k = \frac{\omega - \omega_{21}}{2} \pm \sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}}$$

$$\Rightarrow c_1 \propto e^{i\left[\frac{\omega - \omega_{21}}{2} \pm \sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}}\right]t}$$

$$\Rightarrow c_1 = A e^{i\frac{\omega - \omega_{21}}{2}t} + e^{i\sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}}t} + B e^{i\frac{\omega - \omega_{21}}{2}t} + e^{-i\sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}}t}$$

$$c_1(0) = A + B = 1$$

$$c_2(0) = 0 \Rightarrow c_2(0) = i\left[\frac{\omega - \omega_{21}}{2} + \sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}}\right]A + i\left[\frac{\omega - \omega_{21}}{2} - \sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}}\right]B$$

$$\left[\frac{\omega - \omega_{21}}{2} + \sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}}\right]A + \left[\frac{\omega - \omega_{21}}{2} - \sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}}\right](1 - A) = 0$$

$$2\sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}}A + \frac{\omega - \omega_{21}}{2} - \sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}} = 0$$

$$\Rightarrow A = \frac{1}{2} \left[\frac{-\frac{\omega - \omega_{21}}{2}}{\sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}}} + 1 \right]$$

$$B = \frac{1}{2} \left[\frac{\frac{\omega - \omega_{21}}{2}}{\sqrt{\left(\frac{\omega - \omega_{21}}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}}} + 1 \right]$$

TDPT:

$$c_2 \approx -\frac{i}{\hbar} \int_0^t dt' e^{i\omega_2 t'} \gamma e^{-i\omega_1 t'} = -\frac{i\gamma}{\hbar} \int_0^t dt' e^{i(\omega_2 - \omega_1)t'}$$

$$\approx -\frac{i\gamma}{\hbar} \frac{1}{i(\omega_2 - \omega_1)} (e^{i(\omega_2 - \omega_1)t} - 1)$$

$$\approx \frac{\gamma}{(\omega_2 - \omega_1)\hbar} (e^{-i(\omega_2 - \omega_1)t} - 1)$$

$$|c_2(t)|^2 \approx \frac{\gamma^2}{(\omega_2 - \omega_1)^2 \hbar^2} (2 - 2\cos((\omega_2 - \omega_1)t)) = \frac{4\gamma^2}{(\omega_2 - \omega_1)^2 \hbar^2} \sin^2\left(\frac{\omega_2 - \omega_1}{2} t\right)$$

$$|c_1(t)|^2 \approx 1 - \frac{4\gamma^2}{(\omega_2 - \omega_1)^2 \hbar^2} \sin^2\left(\frac{\omega_2 - \omega_1}{2} t\right)$$

Exact:

$$c_1 = e^{i\frac{\omega_2 - \omega_1}{2}t} \left[(A+B) \cos\left(\sqrt{\left(\frac{\omega_2 - \omega_1}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}} t\right) + (A-B) i \sin(\text{same}) \right]$$

$$= e^{i\frac{\omega_2 - \omega_1}{2}t} \left[\cos\left(\sqrt{\left(\frac{\omega_2 - \omega_1}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}} t\right) - \frac{i}{\sqrt{1 + \frac{4\gamma^2}{\hbar^2(\omega_2 - \omega_1)^2}}} \sin\left(\sqrt{\left(\frac{\omega_2 - \omega_1}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}} t\right) \right]$$

$$|c_1(t)|^2 = \cos^2\left(\sqrt{\left(\frac{\omega_2 - \omega_1}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}} t\right) + \left(1 + \frac{4\gamma^2}{\hbar^2(\omega_2 - \omega_1)^2}\right)^{-1} \sin^2\left(\sqrt{\left(\frac{\omega_2 - \omega_1}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}} t\right)$$

$$\text{and } |c_2(t)|^2 = 1 - |c_1(t)|^2 = \sin^2(\dots) - (\dots)^{-1} \sin^2(\dots) \quad (\omega_2 = \frac{E_2 - E_1}{\hbar})$$

$$\gamma \text{ small: } \left(1 + \frac{4\gamma^2}{\hbar^2(\omega_2 - \omega_1)^2}\right)^{-1} \approx 1 - \frac{4\gamma^2}{\hbar^2(\omega_2 - \omega_1)^2}, \quad \sqrt{\left(\frac{\omega_2 - \omega_1}{2}\right)^2 + \frac{\gamma^2}{\hbar^2}} \approx \frac{\omega_2 - \omega_1}{2}$$

$$\Rightarrow |c_1|^2 \approx 1 - \frac{4\gamma^2}{\hbar^2(\omega_2 - \omega_1)^2} \sin^2\left(\frac{\omega_2 - \omega_1}{2} t\right) \quad (\gamma \ll (\omega_2 - \omega_1)\hbar)$$

same as PT result

If $\omega_2 - \omega_1 \ll \frac{\gamma}{\hbar}$ then

$$c_1 \approx e^{i\frac{\omega_2 - \omega_1}{2}t} \left[\cos\left(\frac{\gamma}{\hbar} t\right) - \frac{\hbar(\omega_2 - \omega_1)}{2\gamma} \sin\left(\frac{\gamma}{\hbar} t\right) \right]$$

$$|c_1|^2 \approx \cos^2\left(\frac{\gamma}{\hbar} t\right) - \frac{\hbar(\omega_2 - \omega_1)}{\gamma} \sin\left(\frac{\gamma}{\hbar} t\right) \cos\left(\frac{\gamma}{\hbar} t\right)$$

2013

QMII-3

$$V(r) = -Ae^{-r/a}$$

spherical symmetry $\Rightarrow \psi = \psi(r)$

also drops off very quickly. So try

$$\psi(r) = \frac{\sqrt{3}}{\sqrt{4\pi R^3}} \begin{cases} 1, & r < R \\ 0, & r > R \end{cases}$$

$$H = -\frac{\hbar^2}{2m} \frac{d^2}{dr^2} - Ae^{-r/a} \quad ; \quad \psi^* H \psi = \frac{3}{4\pi R^3} \int_0^R (-A) e^{-r/a} 4\pi r^2 dr$$

$$\langle \psi | H | \psi \rangle = \frac{-3A}{R^3} \int_0^R r^2 e^{-r/a} dr = \frac{-3A}{R^3} \left[-aR^2 e^{-R/a} + 2a \int_0^R r e^{-r/a} dr \right]$$

$$= \frac{-3A}{R^3} \left[-aR^2 e^{-R/a} - 2a^2 R e^{-R/a} + 2a^2 \int_0^R e^{-r/a} dr \right]$$

$$= \frac{-3A}{R^3} \left[2a^3 - (2a^3 + 2a^2 R + aR^2) e^{-R/a} \right]$$

$$= -6A \left[a^3 R^{-3} - (a^3 R^{-3} + a^2 R^{-2} + aR^{-1}) e^{-R/a} \right] = \bar{H}$$

$$\frac{d}{da} \bar{H} = -6A \left[-3a^3 R^{-4} + (3a^3 R^{-4} + 2a^2 R^{-3} + \frac{a}{2} R^{-2} + a^2 R^{-3} + aR^{-2} + \frac{R^{-1}}{2}) e^{-R/a} \right] = 0$$

$$3a^3 e^{R/a} = 3a^3 + 3a^2 R + \frac{3}{2} a R^2 + \frac{1}{2} R^3$$

$$e^{R/a} = 1 + \frac{R}{a} + \frac{1}{2} \left(\frac{R}{a}\right)^2 + \frac{1}{6} \left(\frac{R}{a}\right)^3$$

no solution.

Try $\psi(r) = C e^{-\alpha r/2a}$

$$1 = \langle \psi | \psi \rangle = C^2 \int_0^\infty r^2 e^{-\frac{\alpha}{2a} r} dr = C^2 4\pi \frac{2a^3}{\alpha^3} \Rightarrow C = \sqrt{\frac{\alpha^3}{8\pi a^3}}$$

$$\frac{d\psi}{dr} = -C \frac{\alpha}{2a} e^{-\alpha r/2a}$$

$$\frac{d}{dr} \left(r^2 \frac{d\psi}{dr} \right) = -C \frac{\alpha}{2a} \left(2r - \frac{\alpha r^2}{2a} \right) e^{-\alpha r/2a}$$

$$\psi^* H \psi = \left(\frac{\hbar^2}{2m} \frac{\alpha}{2a} \left(\frac{2}{r} - \frac{\alpha}{2a} \right) - A e^{-r/a} \right) C^2 e^{-\alpha r/2a}$$

$$\langle \psi | H | \psi \rangle = C^2 \left[\frac{\hbar^2}{2m 2a} \left(8\pi \int_0^\infty r dr e^{-\frac{\alpha}{2a} r} - \frac{2\pi\alpha}{a} \int_0^\infty r^2 dr e^{-\frac{\alpha}{2a} r} \right) - A \int_0^\infty r^2 dr e^{-\frac{\alpha}{2a} r} \right]$$

$\frac{4\pi}{\alpha^2/\alpha^2}$ $\frac{2\pi\alpha^3}{\alpha^3/\alpha^3}$ $\frac{4\pi}{2\alpha^3/(1/\alpha)^3}$

$$\bar{H} = \frac{\alpha^3}{80a^3} \left(\frac{\hbar^2}{2m} \frac{\alpha}{2a} \left(8\pi \frac{a^2}{\alpha^2} - 4\pi \frac{a^2}{\alpha^2} \right) - 8\pi A \frac{a^3}{(1+\alpha)^3} \right)$$

$$= \frac{\hbar^2 \alpha^2}{8ma^2} - \frac{A\alpha^3}{(1+\alpha)^3}$$

$$\frac{\partial \bar{H}}{\partial \alpha} = \frac{\hbar^2 \alpha}{4ma^2} - A \frac{3\alpha^2(1+\alpha)^3 - \alpha^3 \cdot 3(1+\alpha)^2}{(1+\alpha)^6} = \frac{\hbar^2 \alpha}{4ma^2} - \frac{3A\alpha^2}{(1+\alpha)^4} = 0$$

$$\frac{\hbar^2}{4ma^2} (1+\alpha)^4 = 3A\alpha$$

$$A = 32 \text{ MeV} \quad a = 2.2 \text{ fm}$$

$$(1+\alpha)^4 = \frac{12ma^2A}{\hbar^2} \alpha$$

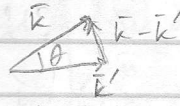
$$m = \frac{m_p + m_n}{m_p + m_n} \approx 470 \text{ MeV}/c^2$$

$$(1+\alpha)^4 \approx 22.4 \alpha \Rightarrow \alpha \approx 1.34$$

$$\Rightarrow \bar{H}_0 = A \left(\frac{\hbar^2}{8ma^2} \alpha^2 - \frac{\alpha^3}{(1+\alpha)^3} \right) \approx A \left(\frac{3}{2} \frac{1}{22.4} \alpha^2 - \frac{\alpha^3}{(1+\alpha)^3} \right)$$

$$\approx -3.58 \text{ MeV}$$

QM1-4 $f(\vec{k}', \vec{k}) = \frac{-1}{4\pi} \frac{2m}{\hbar^2} \int d^3x e^{i(\vec{k}-\vec{k}') \cdot \vec{x}} u(\vec{x})$



$q \equiv |\vec{k} - \vec{k}'| = \sqrt{2k^2 - 2k^2 \cos \theta} = k \sqrt{2 - 2 \cos \theta} = 2k \sin(\theta/2)$

$(\vec{k} - \vec{k}') \cdot \vec{x} = 2k \sin(\theta/2) r \cos \theta'$, $\vec{k} - \vec{k}'$ along z

$$\int d\Omega e^{i(\vec{k}-\vec{k}') \cdot \vec{x}} = \int_{-1}^1 2\pi \sin \theta' e^{i2k \sin(\theta/2) r \cos \theta'} = \frac{2\pi}{iqr} (e^{iqr} - e^{-iqr}) = \frac{4\pi}{qr} \sin(qr)$$

$$f(A) = \frac{-2m}{\hbar^2} \frac{1}{q} \int_0^\infty r dr \sin(qr) u_0 e^{-r^2/R^2}$$

$$= \frac{-2m u_0}{\hbar^2 q} \int_0^\infty dr r \sin(qr) e^{-r^2/R^2} = \frac{-m u_0}{i\hbar^2 q} \left[\int_0^\infty dr r e^{iqr - \frac{r^2}{R^2}} - \int_0^\infty dr r e^{-iqr - \frac{r^2}{R^2}} \right]$$

$$e^{iqr - \frac{r^2}{R^2}} = e^{-\left(\frac{r}{R} - iqR/2\right)^2} e^{-q^2 R^2/4} \quad e^{-iqr - \frac{r^2}{R^2}} = e^{-\left(\frac{r}{R} + iqR/2\right)^2} e^{-q^2 R^2/4}$$

$$= \frac{-m u_0}{i\hbar^2 q} e^{-q^2 R^2/4} \left[\int_{-iqR/2}^{\infty} (u + iqR/2) du e^{-u^2} - \int_{iqR/2}^{\infty} (u - iqR/2) du e^{-u^2} \right] \quad u = \frac{r}{R} + iqR/2 \quad du = \frac{dr}{R}$$

$$\int_{-iqR/2}^{\infty} u du e^{-u^2} + iqR/2 \sqrt{\pi}$$

$$= \frac{-m u_0 R^3 \sqrt{\pi}}{2\hbar^2} e^{-q^2 R^2/4}$$

$$\Rightarrow \frac{d\sigma}{d\Omega} = |f(\theta)|^2 = u^2 R^2 \exp\left(-\frac{q^2 R^2}{2}\right)$$

$$u = \frac{\sqrt{\pi} m u_0 R^2}{2\hbar^2}$$

2013

$$\sigma = u^2 R^2 \int_{-1}^1 2\pi dm e^{-k^2 R^2 (1-m)} = 2\pi u^2 R^2 e^{-k^2 R^2} \int_{-1}^1 dm e^{k^2 R^2 m}$$

$$m = \cos\theta = 1 - 2\sin^2\theta/2 \Rightarrow \sin^2\theta/2 = \frac{1}{2}(1-m) \quad \frac{e^{k^2 R^2} - e^{-k^2 R^2}}{k^2 R^2}$$

$$\sigma = \frac{2\pi u^2}{k^2} (1 - e^{-2k^2 R^2})$$

QM11-5 ++, +- , -+ , -- index order $\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ $\sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$ $\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$$\chi_0 = \frac{1}{\sqrt{2}} \left(|h\rangle \otimes |g\rangle - |g\rangle \otimes |h\rangle \right)$$

$$\chi_1 = \frac{1}{\sqrt{2}} \left(|h\rangle \otimes |g\rangle + |g\rangle \otimes |h\rangle \right)$$

$$\chi_2 = |h\rangle \otimes |g\rangle$$

$$\chi_3 = |g\rangle \otimes |g\rangle$$

$$\chi_0 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix} \quad \chi_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix}$$

$$\chi_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad \chi_3 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$S_{total}^2 = (\vec{S}_1 + \vec{S}_2)^2 = \frac{\hbar^2}{4} \left((\sigma_1 + \sigma_1)^2 + (\sigma_2 + \sigma_2)^2 + (\sigma_3 + \sigma_3)^2 \right)$$

$$= \frac{\hbar^2}{4} \left[\begin{pmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ -1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{pmatrix}^2 + \begin{pmatrix} 0 & -i & -i & 0 \\ i & 0 & 0 & -i \\ i & 0 & 0 & -i \\ 0 & i & i & 0 \end{pmatrix}^2 + \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix}^2 \right]$$

$$= \frac{\hbar^2}{4} \left[\begin{pmatrix} 2 & 0 & 0 & 2 \\ 0 & 2 & 2 & 0 \\ 0 & 2 & 2 & 0 \\ 2 & 0 & 0 & 2 \end{pmatrix} + \begin{pmatrix} 2 & 0 & 0 & -2 \\ 0 & 0 & 0 & 0 \\ 0 & 2 & 2 & 0 \\ -2 & 0 & 0 & 2 \end{pmatrix} + \begin{pmatrix} 4 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 4 \end{pmatrix} \right]$$

$$= \frac{\hbar^2}{4} \begin{pmatrix} 8 & 0 & 0 & 0 \\ 0 & 4 & 4 & 0 \\ 0 & 4 & 4 & 0 \\ 0 & 0 & 0 & 8 \end{pmatrix} = \hbar^2 \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix}$$

eigenvalues $\hbar^2 \lambda$:
 $(2-\lambda)^2 (1-\lambda)^2 - 1 = (\lambda-2)^2 \lambda = 0$
 $\Rightarrow \lambda = 0, \lambda = 2$

$$S_{total}^2 \chi_0 = \hbar^2 0 = 0 \quad (\text{singlet})$$

$$S_{total}^2 \chi_1 = \hbar^2 2 \chi_1 = 2\hbar^2 \chi_1$$

$$S_{total}^2 \chi_2 = 2\hbar^2 \chi_2$$

$$S_{total}^2 \chi_3 = 2\hbar^2 \chi_3$$

(triplet)

para: singlet $\chi_0 \Rightarrow \psi_0(\vec{r}_1, \vec{r}_2)$ symmetric (total wavefunction antisym.)
 ortho: $\chi_1 \Rightarrow \psi_1(\vec{r}_1, \vec{r}_2)$ antisymmetric (total wavefunction symmetric under exchange)

antisymmetric $\psi \Rightarrow e^-$ further apart because

$$\psi|_{\vec{r}_1 = \vec{r}_2 = 0} = \psi(\vec{r}_1, \vec{r}_1) = -\psi(\vec{r}_1, \vec{r}_1) = 0$$

\Rightarrow lower energy (weaker e-e interaction) for ortho state

2012 CM1 use $x_{\pm} = \frac{1}{2}(x \pm y)$, note $x = x_+ + x_-$, $y = x_+ - x_-$

$$x^2 + y^2 = 2(x_+^2 + x_-^2), \quad xy = x_+^2 - x_-^2$$

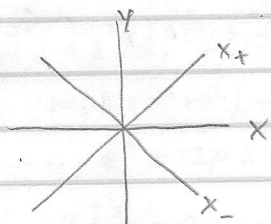
$$L = \frac{1}{2}m(2\dot{x}_+^2 + 2\dot{x}_-^2 + 2\alpha\dot{x}_+^2 - 2\alpha\dot{x}_-^2) - \frac{1}{2}k(2x_+^2 + 2x_-^2 + 2\beta x_+ - 2\beta x_-)$$

$$= m(1+\alpha)\dot{x}_+^2 + m(1-\alpha)\dot{x}_-^2 - k(1+\beta)x_+^2 - k(1-\beta)x_-^2$$

independent oscillators: $\omega_+ = \sqrt{\frac{k}{m} \frac{1+\beta}{1+\alpha}}$, $\omega_- = \sqrt{\frac{k}{m} \frac{1-\beta}{1-\alpha}}$

stable oscillation: ω_{\pm} real $\Leftrightarrow (\alpha < 1 \text{ and } \beta < 1)$ or $(\alpha > 1 \text{ and } \beta > 1)$

eigenvectors: x_+ and x_- ($x+y$ and $x-y$)



Relative frequencies of x_+ , x_- vary with α, β but the eigenmodes themselves do not.

Alternatively: $m\ddot{x} + m\alpha\ddot{y} + kx + k\beta y = 0 \Rightarrow T = \begin{pmatrix} m & m\alpha \\ m\alpha & m \end{pmatrix} \quad V = \begin{pmatrix} k & k\beta \\ k\beta & k \end{pmatrix}$

$$T\ddot{\vec{x}} + V\vec{x} = 0$$

$$(-\omega^2 T + V)\vec{x} = 0 \Rightarrow$$

$$\det \begin{pmatrix} -\omega^2 m + k & -\omega^2 m\alpha + k\beta \\ -\omega^2 m\alpha + k\beta & -\omega^2 m + k \end{pmatrix} = (k - \omega^2 m)^2 - (k\beta - \omega^2 m\alpha)^2 = 0$$

$$= \omega^4 m^2 (1 - \alpha^2) - 2\omega^2 km(1 - \beta\alpha) + k^2 (1 + \beta^2)$$

$$\Rightarrow \omega^2 = \frac{k m (1 - \beta\alpha) \pm \sqrt{k^2 m^2 (1 - \beta\alpha)^2 - m^2 (1 - \alpha^2) k^2 (1 - \beta^2)}}{m^2 (1 - \alpha^2)} = \frac{k}{m} \frac{1 - \beta\alpha \pm \sqrt{(1 - 2\beta\alpha + \beta^2\alpha^2) - (1 - \alpha^2)(1 - \beta^2)}}{1 - \alpha^2}$$

$$= \frac{k}{m} \frac{1 - \beta\alpha \pm \alpha \mp \beta}{(1 - \alpha)(1 + \alpha)} = \frac{k(1 \mp \beta)(1 \pm \alpha)}{m(1 - \alpha)(1 + \alpha)} = \frac{k}{m} \frac{1 \mp \beta}{1 \mp \alpha}$$

$$-\omega^2 T + V = k \begin{pmatrix} 1 - \frac{1 \mp \beta}{1 \mp \alpha} & \beta - \frac{1 \mp \beta}{1 \mp \alpha} \alpha \\ \beta - \frac{1 \mp \beta}{1 \mp \alpha} \alpha & 1 - \frac{1 \mp \beta}{1 \mp \alpha} \alpha \end{pmatrix} = \frac{k}{1 \mp \alpha} \begin{pmatrix} \mp \alpha \pm \beta & \beta(1 \mp \alpha) - \alpha(1 \mp \beta) \\ \beta - \alpha & \pm(\beta - \alpha) \end{pmatrix} = \frac{k}{1 \mp \alpha} \begin{pmatrix} \pm 1 & 1 \\ 1 & \pm 1 \end{pmatrix}$$

\Rightarrow vectors $\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}$